

Heat 2D - free light version

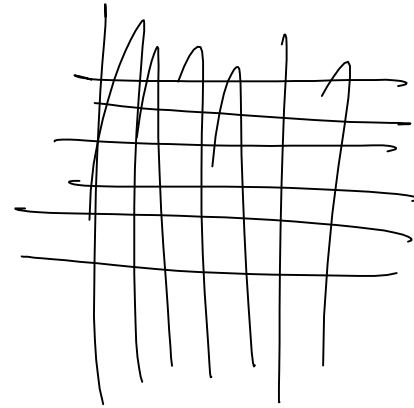
www.buildingphysics.com

Buildingphysics.com
Software for heat transfer and ground heat

HEAT2 - Heat transfer in two dimensions

Now supporting over 40 languages!

F(x,y)



DIN (Deutsches Institut für Normung, DIN V 4108-4) is also available.

Extensive window frame analysis has been implemented according to ISO 10077.



Support and manuals also available in German, see www.buildingphysics.de



For sales and support in the CIS-countries, Latvia, Lithuania, and Estonia, see www.buildingphysics.ru

[Click here for current version update info](#)

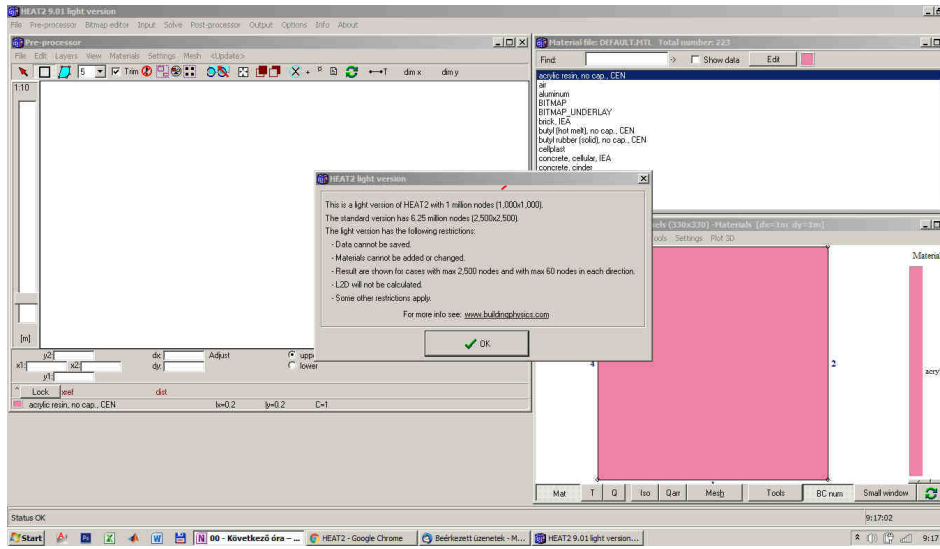
[Free light version: Click here to download a free light version](#)

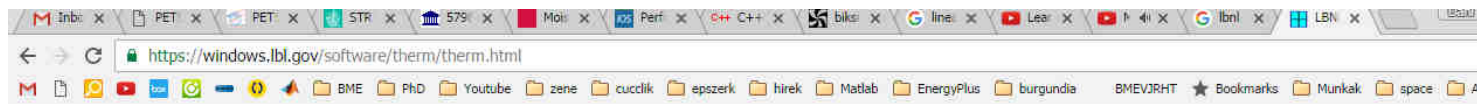


YouTube clips:

- [Input example using rectangles, polygons, and bitmaps](#)
- [Input example using bitmaps. Also shows a bitmap of a window frame that is imported and filled with different materials.](#)

Tips for reading for beginners: For a quick start read Chapter 4 (pages 23-27) in [Manual HEAT2 5.0](#). The example in chapter 8 (pages 117-121) would also give a short introduction. After this, look at the update manuals for HEAT2 6.0, HEAT2 7.0, etc. Also see the EN ISO test cases: [ISO 10211](#) & [10077-2](#)





THERM

THERM 6.3 For NFRC Certification and modeling complex glazing systems	THERM 7.4 For modeling vacuum glazing, deflected glass, vertical venetian blinds, cellular shades and perforated screens
Forum For questions about THERM	Forum For questions about THERM
Knowledge Base (Check here first if you are experiencing a problem with the software)	Knowledge Base (Check here first if you are experiencing a problem with the software)
Documentation	Documentation
Tutorials	Tutorials

Two-Dimensional Building Heat-Transfer Modeling

THERM is a state-of-the-art computer program developed at Lawrence Berkeley National Laboratory (LBNL) for use by building component manufacturers, engineers, educators, students, architects, and others interested in heat transfer. Using THERM, you can model two-dimensional heat-transfer effects in building components such as windows, walls, foundations, roofs, and doors; appliances; and other products where thermal bridges are of concern. THERM's heat-transfer analysis allows you to evaluate a product's energy efficiency and local temperature patterns, which may relate directly to problems with condensation, moisture damage, and structural integrity.

THERM's two-dimensional conduction heat-transfer analysis is based on the finite-element method, which can model the complicated geometries of building products. See [Components](#) for more details.

THERM can be used with the Berkeley Lab WINDOW program. THERM's results can be used with WINDOW's center-of-glass optical and thermal models to determine total window product U-factors and Solar Heat Gain Coefficients. These values can be used, in turn, with the [RESFEN](#) program, which calculates total annual energy requirements in typical residences throughout the United States.

[Components](#)

THERM 7.4

Last Updated: 10/03/2015

If you find bugs, or have comments about this version, we now have an [online forum](#) where you can ask questions and respond to questions by others. Getting feedback from users is how we improve the program.

THERM 7 contains many new modeling features, including:

- Deflection Model
- Vacuum Glazing
- Vertical Louvered Blinds
- Perforated Screens
- Honeycomb shades
- Dynamic Glazing (Thermochromic and Electrochromic)

Latest Version

[THERM 7.4.3](#)
(7.4.3)
(10/03/2015)

[Release Notes](#) -- Please read these before running this version !

This version is compatible with WINDOW 7.4.6.

- If you try to import THERM 7.4.3 files into earlier versions of WINDOW 7.3, WINDOW may crash; in this case upgrade to this latest version of WINDOW 7.4

Download Registration

Before you can download software from this website you need to login. If you don't have an account, you need to Create an account first.


This registration page will not work unless you have enabled Cookies in your browser.

Sign in with your Account

E-mail:

Password:

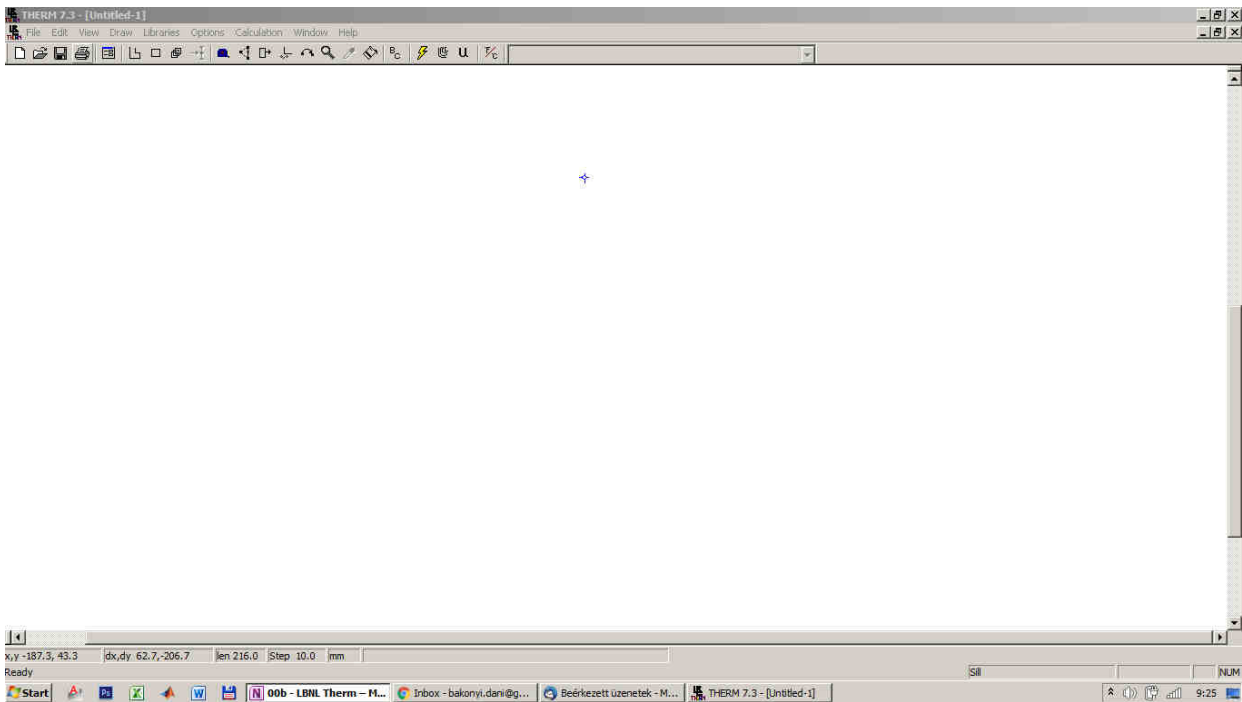
**You need to login first.
Please enter your login details.**

Remember me on this computer. 

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Don't have an Account yet?
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If you have questions or problems with the registration, please contact WindowHelp@lbl.gov



vektor $\vec{v} = (v_1, v_2, v_3, \dots)$

mátrix $A = \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \\ a_{31} & a_{32} \end{pmatrix}$

3×2
 \uparrow oszlopok száma
 \uparrow sorok száma

vektor műveletek:

$$\vec{u} + \vec{v} = (u_1 + v_1, u_2 + v_2, u_3 + v_3)$$

$$\vec{u} - \vec{v} = (u_1 - v_1, u_2 - v_2, u_3 - v_3)$$

$$\alpha \cdot \vec{u} = (\alpha u_1, \alpha u_2, \alpha u_3) \quad \text{skaláris szorzás}$$

$$\|\vec{u}\| = \sqrt{u_1^2 + u_2^2 + u_3^2} \quad \text{norma}$$

$$\vec{u} \cdot \vec{v} = u_1 v_1 + u_2 v_2 + u_3 v_3$$

$$\|\vec{u}\| \cdot \|\vec{v}\| \cdot \cos(\angle) \quad \text{skaláris szorzat}$$

$$\vec{u} \times \vec{v} = (u_2 v_3 - u_3 v_2, u_3 v_1 - u_1 v_3, u_1 v_2 - u_2 v_1) \quad \text{vektoriális szorzat}$$

$$\|\vec{u} \times \vec{v}\| = \|\vec{u}\| \|\vec{v}\| \sin(\angle)$$

$$\vec{u} \times \vec{v} \neq \vec{v} \times \vec{u}$$

Mátrix műveletek:

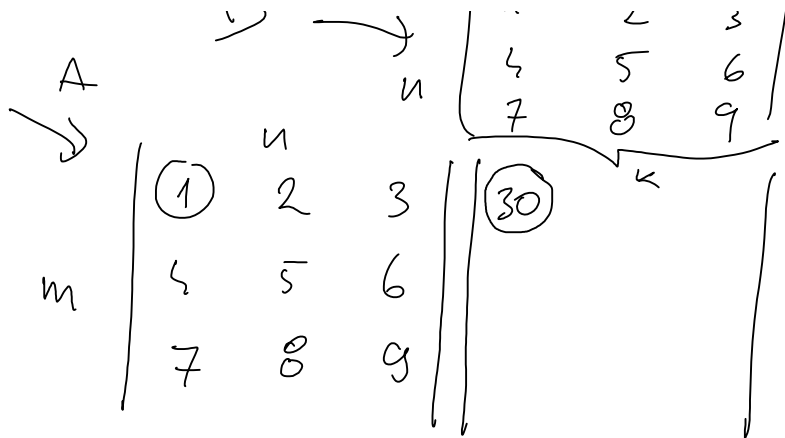
$$A + B = C \quad c_{ij} = a_{ij} + b_{ij}$$

$$A - B = C \quad c_{ij} = a_{ij} - b_{ij}$$

$$A \cdot B = C \quad c_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

$A \quad B \rightarrow$

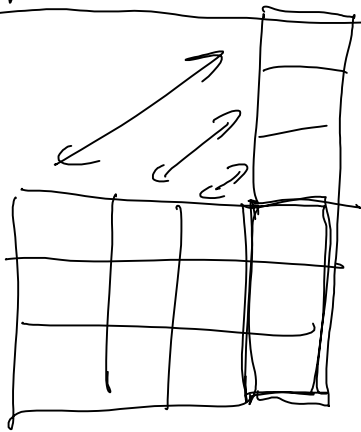
1	2	3
4	5	6
7	8	9



① A oszlopai száma
 B sorai száma

② C - az A sorai száma
 B oszlopai száma

$$\begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix} \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 \\ 15 \\ \dots \end{pmatrix}$$



A A^{-1} inverz

$A^{-1} \cdot A = I$ ← ekkor I az egységmátrix
 identity-matrix

$A \cdot \vec{x} = \vec{b}$
 A : mátrix
 \vec{x} : ismeretlen vektor
 \vec{b} : ismert vektor

T ismeretlenek
vektor

$$\underbrace{A^{-1} A} \cdot T = A^{-1} \cdot b$$

$$I \cdot T = A^{-1} b$$

$$\left| \begin{array}{ccc|c} 1 & 0 & 0 & T_1 \\ 0 & 1 & 0 & T_2 \\ 0 & 0 & 1 & T_3 \end{array} \right| = \left| \begin{array}{c} T_1 \\ T_2 \\ T_3 \end{array} \right|$$

$$\boxed{T} = A^{-1} \cdot b$$

elimináció

Gauss-Jordan elimináció

$$1x_1 + 2x_2 = 5$$

$$3x_1 + 9x_2 = 21$$

$$\left| \begin{array}{cc|c} 1 & 2 & 5 \\ 3 & 9 & 21 \end{array} \right| \begin{array}{l} x_1 \\ x_2 \end{array} = \begin{array}{c} 5 \\ 21 \end{array}$$

↗ kicserélvi sorokat
→ egyik sor NX kezdődjen
Ettől kezdve sorok

↘ egyik sor szorzásca az
konstanssal

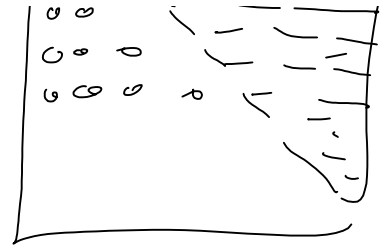
$$\left| \begin{array}{cc|c} 1 & 2 & 5 \end{array} \right| \begin{array}{c} x_1 \\ x_2 \end{array} = 5$$

$$u = 16392$$

$$u \left| \begin{array}{ccc|ccc} & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \\ & & & & & \end{array} \right|$$

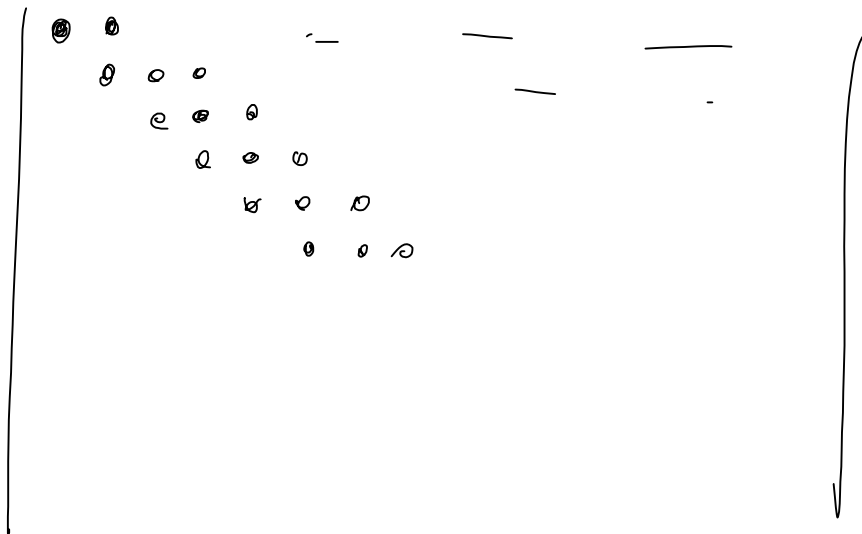
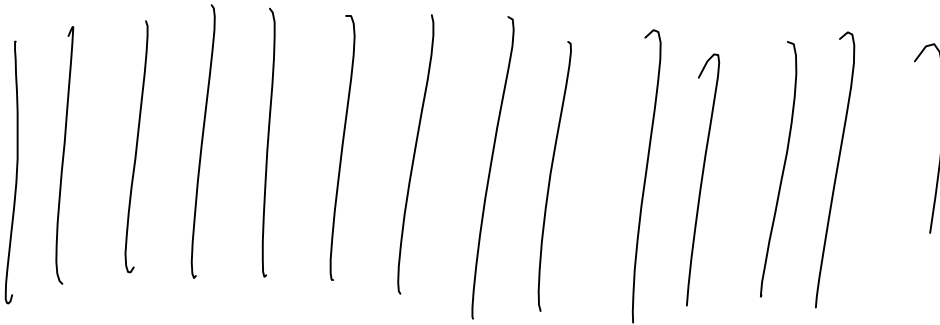
$$\left| \begin{array}{cc|c} 1 & 2 & x_1 \\ 0 & 3 & x_2 \end{array} \right| = \left| \begin{array}{c} 5 \\ 6 \end{array} \right| \rightarrow x_2$$

u



$$\left| \begin{array}{cc|c} 1 & 2 & x_1 \\ 0 & 1 & x_2 \end{array} \right| = \left| \begin{array}{c} 5 \\ 2 \end{array} \right| \quad /:3$$

$$\left| \begin{array}{cc|c} 1 & 0 & x_1 \\ 0 & 1 & x_2 \end{array} \right| = \left| \begin{array}{c} 5 \\ 2 \end{array} \right| \quad /-2 \times 2.\text{sur}$$



ritka
matriks

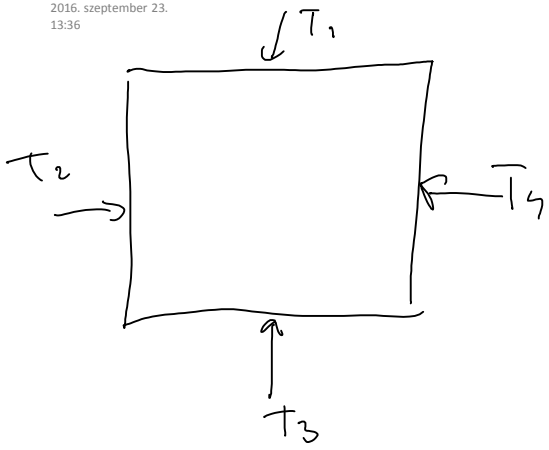
$$\begin{aligned}
 x_1 + 2x_2 &= 1 \\
 2x_1 + 4x_2 &= 2 \quad \downarrow
 \end{aligned}$$

$$\left| \begin{array}{c|c} \textcircled{1} & 2 \\ \cancel{2} & 4 \end{array} \right|$$

$$\left| \begin{array}{c|c} 2 & 2 \\ 0 & 0 \end{array} \right|$$

$$\left| \begin{array}{c} 4 \\ 5 \\ 0 \end{array} \right|$$

$$| 1 \quad 2 \quad 3 | \textcircled{0}$$



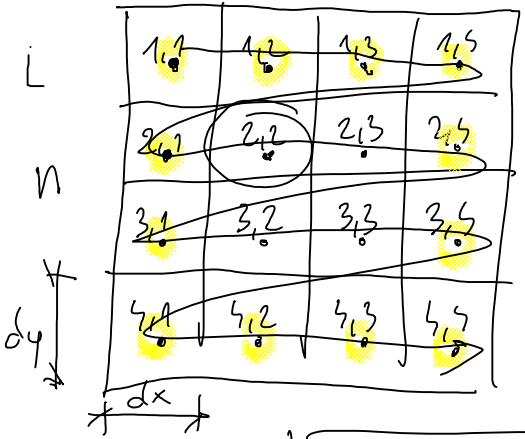
$$\lambda_x \frac{\partial^2 T}{\partial x^2} + \lambda_y \frac{\partial^2 T}{\partial y^2} = 0$$

$$\frac{\partial^2 T}{\partial x^2} = \frac{T(x+dx) - 2T(x) + T(x-dx)}{dx^2}$$

$i=1 \quad j=1$

$(i-1) * Nx + j$

1.) diszkrétizáció



1,1 : $T_{1,1} = 10$
 ...
 2,1 : $T_{2,1} = 10$

$$T_{2,2} + \frac{\lambda_x}{dx^2} T_{2,1} - \frac{2\lambda_x}{dx^2} T_{2,2} + \frac{\lambda_x}{dx^2} T_{2,3} + \frac{\lambda_y}{dy^2} T_{1,2} - \frac{2\lambda_y}{dy^2} T_{2,2} + \frac{\lambda_y}{dy^2} T_{3,2} = 0$$

2.) vektorizáció

$$K \cdot T = b$$

T mátrix

$$T = \begin{pmatrix} T_{1,1} \\ T_{2,2} \\ T_{2,3} \\ T_{1,4} \end{pmatrix}$$

$$I = \begin{array}{c} \hline \overline{T_{1,3}} \\ \overline{T_{1,5}} \\ \hline 1_{2,1} \\ \hline T_{2,2} \\ \overline{T_{2,3}} \\ \overline{T_{2,5}} \\ \hline \overline{T_{3,1}} \\ \vdots \end{array}$$

K matrix

$1_{1,1}$	$1_{1,2}$	$1_{1,3}$	$1_{1,5}$	$2_{1,1}$	$2_{1,2}$	$2_{1,3}$...	$3_{1,2}$	
1	0	0	0	0					
0	1	0	0	0	...				
0	0	1	0	0	...				
0	0	0	1	0	...				
0	0	0	0	1	...				
	$\frac{\lambda_y}{dy^2}$	0	0	$\frac{\lambda_x}{dx^2}$	$-\frac{2\lambda_x}{dx^2}$	$-\frac{2\lambda_y}{dy^2}$	$\frac{\lambda_x}{dx^2}$...	$\frac{\lambda_y}{dy^2}$

$T_{1,1}$	10
$T_{2,2}$	10
$T_{1,3}$	10
$T_{1,5}$	10
$T_{2,1}$	0
$T_{2,2}$	0
$T_{2,3}$	0
\vdots	